



# DOWNLOAD

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<p style="text-align: center;"><b>Formulas</b></p> <p>4. <math>S = \frac{(v_f^2 - v_i^2)}{2a}</math></p> <p>Where:  <math>S</math> = Distance  <math>v_f</math> = Final Velocity  <math>v_i</math> = Initial Velocity  <math>a</math> = Acceleration  <math>t</math> = time</p>	<p><b>4 Steps in Using the Formula</b></p> <ol style="list-style-type: none"> <li>1. Gather all the data. 4 in all.</li> <li>2. Look from the formulas where all the given data are present.</li> <li>3. Substitute all the data in the formula to find the unknown.</li> <li>4. Just do it!</li> </ol> <p><b>Freeing Bodies</b></p> $S = \frac{1}{2}gt^2$ <p>Where:  <math>g</math> = gravity  <math>g</math> = + when  <math>g</math> = - when</p>
<p><b>Projectiles</b></p> <p>The equation of projectile:  <math>y = x \tan \alpha - \frac{gx^2}{2v_0^2 \cos^2 \alpha}</math></p> <p><b>Special Formulas:</b></p> <ol style="list-style-type: none"> <li>1. <math>t = \frac{2v_0 \sin \alpha}{g}</math></li> <li>2. <math>R = v_0 t \cos \alpha</math></li> <li>3. <math>R = \frac{v_0^2 \sin 2\alpha}{g}</math></li> <li>4. <math>R_{max} = \frac{v_0^2}{g}</math>, <math>\alpha = 45^\circ</math></li> <li>5. <math>H_{max} = \frac{v_0^2 \sin^2 \alpha}{2g}</math></li> </ol> <p>Where:  <math>R</math> = Range  <math>R_{max}</math> = Maximum Range  <math>H_{max}</math> = Maximum Height</p>	<p><b>Rotation(Angular Motion)"allinrad"</b></p> <p><b>Uniform Motion:</b>  <math>\theta = \omega t</math></p> <p><b>Uniform Acceleration:</b></p> <ol style="list-style-type: none"> <li>1. <math>\alpha = \frac{\omega_f - \omega_i}{t}</math></li> <li>2. <math>\theta = \omega_i t + \frac{1}{2} \alpha t^2</math></li> <li>3. <math>\omega_f^2 = \omega_i^2 + 2\alpha\theta</math></li> </ol> <p>Where:  <math>\alpha</math> = angular acceleration, <math>rad/sec^2</math>  <math>\theta</math> = angular displacement, <math>rad/sec</math>  <math>\omega</math> = angular velocity, <math>rad</math></p> <p><b>Relationship between Translation and Rotation</b></p> $s = r\theta \quad v = r\omega$ $a = r\alpha$



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